

THE PSEUDOMETRIC TOPOLOGY OF A SEMINORM IS A VECTOR TOPOLOGY

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Abstract

We show that the pseudometric topology of a seminorm is a vector topology. The proof here is a General Topological proof based on net convergence in a topological space.

Keywords: net convergence, seminorm, pseudometric topology, vector topology

1 LANGUAGE AND NOTATION Our language, notation and citations shall be pretty standard, as found, for example, in [1] and [2]. The *pseudometric topology* τ_d of the pseudometric space (X, d) holds a commanding position in General Topology. And you are not very likely to be admonished for *heresy* if you define General Topology as the *study of the pseudometric topology*. J.D. Pryce, in his book [3], observed that the Euclidean n -space $(\mathbb{R}^n, \|\cdot\|_n)$ holds a commanding position in Analysis. But the topology $\tau_{\|\cdot\|_n}$ of $(\mathbb{R}^n, \|\cdot\|_n)$ is a pseudometric topology. Undiluted *General Topology (GT)* constitutes about seventy-five percent (75%) of the theory of *Topological Vector Spaces (TVS)*. And so, it should not be surprising, therefore, that the *pseudometric topology of the seminorm* also holds a commanding position in **TVS** theory. At the peak of the subject of **TVS** are the theory of *Locally Convex Spaces* and *Duality Theory*. And one may not be very incorrect to define these subjects as the *study of the pseudometric topology of the seminorm*. For an instance, the popular strong topology $\beta(X, Y)$ of the duality $\langle X, Y \rangle$ is generated by the collection of all the lower semicontinuous seminorms of the duality[4].

To embark on the study of **TVS** without first taking the pains to wade through *the oppressive detail of*

General Topology \equiv Open set, Closed set, Closure, Net and Filter convergence, the pseudometric topology, the product topology, Continuity, Compactness, Connectedness Completion, Uniform Space, Topological Group, is only good for geniuses. I repeat: *More than 75% of the subject of TVS is undiluted, naked, unadulterated General Topology from Open Set to Topological Group, e.g., a topological group is a uniform space, and a topological vector space is a topological group. A dominant concept in Locally Convex Space Theory is Equicontinuity. And, Equicontinuity is a Uniform Space concept. Sterling K. Berberian, in a private communication, once scolded me “.....” but that (Uniform Space theory) is part of General Education.....”.* **Observation** A motivation for the study of *Uniform Spaces* and a key example are furnished by the pseudometric topology.

In what follows, the reader is assumed familiar with the beginnings of General Topology. By \mathbb{R} we denote the *real numbers*, \mathbb{C} denotes the *complex numbers* and \mathbb{N} denotes the *positive integers* 1, 2,

Let $X \neq \emptyset$. A subfamily of 2^X , τ , say, is called a *topology on X*, and the pair (X, τ) called a *topological space*, if

TOP 1 $\emptyset, X \in \tau$,

TOP 2 τ is closed under finite intersection, and

TOP 3 τ is closed under arbitrary union.

If $G \in \tau$, G is called an *open set* of τ or of (X, τ) .

If (X, τ) is a topological space, $x_0 \in X$, $G \in \tau$, $\emptyset \neq A \subseteq X$ and $x_0 \in G \subseteq A$, then A is called a *neighbourhood* x_0 .

Let $X \neq \emptyset$, $\emptyset \neq A \subseteq X$, (I, \leq) a *directed set*, and $(x_i)_{i \in (I, \leq)}$ a *net* in X based on the directed set (I, \leq) . The net $(x_i)_{i \in (I, \leq)}$ is said to be *eventually in A* if there exists $\delta \in I$ such that $x_i \in A$ for all $i \in I$, $i \geq \delta$. And we write $x_i \in A$ *eventually*.

Let (X, τ) be a *topological space* and $x_0 \in X$. If the net $(x_i)_{i \in (I, \leq)}$ in X is eventually in every neighbourhood of x_0 , we say that $(x_i)_{i \in (I, \leq)}$ *converges to* x_0 , and we may write $x_i \xrightarrow{\tau} x_0$

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The words *function*, *map* and *mapping* are synonymous. We indicate by /// the end or absence of a proof.

2 THE PSEUDOMETRIC TOPOLOGY Let $X \neq \emptyset$. A function

$$d : X \times X \rightarrow \mathbb{R},$$

such that, for $x, y, z \in X$,

PSDM 1 $d(x, y) \geq 0$ and $d(x, x) = 0$ (*Positivity of the pseudometric*),

PSDM 2 $d(x, y) = d(y, x)$ (*Symmetry of the pseudometric*) and

PSDM 3 $d(x, z) \leq d(x, y) + d(y, z)$ (*The Triangle Inequality*)

is called a *pseudometric* on X , and the pair (X, d) then also called a *pseudometric space*. A pseudometric d on X with the additional property

METC $d(x, y) = 0$ if and only if $x = y$,

is called a *metric on X* , and the pair (X, d) then also called a *metric space*.

Let (X, d) be a pseudometric space, $x_0 \in X$, $r \in \mathbb{R}$, $r > 0$. The set

$$B_d(x_0, r) \equiv \{x \in X : d(x, x_0) < r\}$$

is called a *ball in (X, d) of radius r centered on x_0* . Clearly, $x_0 \in B_d(x_0, r)$.

THEOREM 1 *The Open Ball Theorem* Let (X, d) be a pseudometric space, $x_0 \in X$, $r > 0$, $B_d(x_0, r)$ a ball in (X, d) and $a \in B_d(x_0, r)$. Then, there exists $r' > 0$ such that $B_d(a, r') \subseteq B_d(x_0, r)$. ///

Define

$$\tau_d \equiv \{\emptyset, X\} \cup \{\emptyset \neq G \subseteq X : G \text{ is a union of balls}\}.$$

THEOREM 2 τ_d is a topology on X . ///

The topology τ_d is called the *pseudometric topology* of d or of (X, d) , and, of course, (X, τ_d) is called a *pseudometric topological space*. If d is a metric, of course, τ_d is called the *metric topology* of d or of (X, d) , and (X, τ_d) called a *metric topological space*.

Example 3 *The absolute value metric*

$$d_{|} : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$$

$$(x, y) \mapsto |x - y|$$

on \mathbb{R} , yields the metric topology $\tau_{d_{|}}$ on \mathbb{R} called, in this paper, the *topology of \mathbb{R}* . Clearly if $a \in \mathbb{R}$, and $r > 0$, the ball of radius r centered on a is

$$B_{d_{|}}(a, r) \equiv \{x \in \mathbb{R} : d_{|}(x, a) < r\}$$

$$= \{x \in \mathbb{R} : |x - a| < r\}$$

$$= (a - r, a + r),$$

the finite open interval with extremities $a - r$ and $a + r$. See

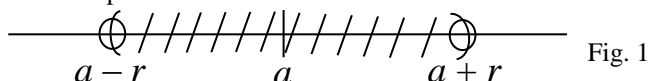


Figure 1 above. So, the open sets of the topology of \mathbb{R} are \emptyset , \mathbb{R} and unions of finite open intervals. The topology of \mathbb{R} , $\tau_{d_{|}}$ is denoted $\tau_{\mathbb{R}}$ in this paper. So, $\tau_{d_{|}} = \tau_{\mathbb{R}}$.

FACT 4 Let (X, τ_d) be a pseudometric topological space, $x_0 \in X$ and $\emptyset \neq A \subseteq X$. Then, A is a τ_d -neighbourhood of x_0 if and only if there exists a ball $B_d(x_0, r)$, $r > 0$, such that $B_d(x_0, r) \subseteq A$.

Proof Immediate from the definition of τ_d and the definition of a neighbourhood, noting that the ball $B_d(x_0, r)$ is itself a neighbourhood of x_0 . ///

THEOREM 5 Let (X, τ_d) be a pseudometric topological space, $x_0 \in X$ and $(x_i)_{i \in (I, \leq)}$ a net in X . Then, $(x_i)_{i \in (I, \leq)}$ τ_d -converges to x_0

$$\Leftrightarrow^1$$

Whenever given $r > 0$, $(x_i)_{i \in (I, \leq)}$ is eventually in $B_d(x_0, r)$

$$\Leftrightarrow^2$$

For every $r > 0$, there exists $i_0 \in I$ such that $d(x_i, x_0) < r$ for all $i \in I, i \geq i_0$.

That is,

$$|d(x_i, x_0) - 0| < r \text{ for all } i \in I, i \geq i_0.$$

\Leftrightarrow^3

The net $(d(x_i, x_0))_{i \in (I, \leq)}$ $\tau_{\mathbb{R}}$ -converges to 0.

Proof Immediate from definitions. ///

COROLLARY 6 Let $x_0 \in \mathbb{R}$. The net $(x_i)_{i \in (I, \leq)}$ in \mathbb{R} $\tau_{\mathbb{R}}$ -converges to x_0

\Leftrightarrow

Whenever given $r > 0$, there exists $i_0 \in I$ such that

$$|x_i - x_0| < r \text{ for all } i \in I, i \geq i_0.$$

\Leftrightarrow

$$x_i - x_0 \xrightarrow{\tau_{\mathbb{R}}} 0$$

(i.e., the net $(x_i - x_0)_{i \in (I, \leq)}$ $\tau_{\mathbb{R}}$ -converges to 0. ///

THEOREM 7 Let $(x_i)_{i \in (I, \leq)}$ and $(y_i)_{i \in (I, \leq)}$ be nets in \mathbb{R} based on the same directed set (I, \leq) . Suppose $x, y, \alpha \in \mathbb{R}$ and that

$$x_i \xrightarrow{\tau_{\mathbb{R}}} x$$

and

$$y_i \xrightarrow{\tau_{\mathbb{R}}} y.$$

Then,

$$(i) \quad x_i + y_i \xrightarrow{\tau_{\mathbb{R}}} x + y$$

and

$$(ii) \quad \alpha x_i \xrightarrow{\tau_{\mathbb{R}}} \alpha x.$$

Proof (i): Let $r > 0$. By hypotheses and COROLLARY 6, there exist $i_0', i_0'' \in I$ such that

$$\left. \begin{aligned} i \geq i_0' &\Rightarrow |x_i - x_0| < \frac{r}{2} \\ \text{and } i \geq i_0'' &\Rightarrow |y_i - y| < \frac{r}{2} \end{aligned} \right\} \dots\dots\dots (*)$$

Since (I, \leq) is a directed set, there exists $i_0 \in I$ such that $i_0 \geq i_0'$ and $i_0 \geq i_0''$. Hence,

$$i \geq i_0 \Rightarrow |x_i - x_0| < \frac{r}{2}, |y_i - y| < \frac{r}{2}$$

By arguments from *Elementary Real Analysis*, therefore,

$$\begin{aligned} i \geq i_0 &\Rightarrow |x_i + y_i - (x + y)| = |x_i - x + y_i - y| \leq |x_i - x| + |y_i - y| \\ &< \frac{r}{2} + \frac{r}{2} = r. \end{aligned}$$

(ii): If $\alpha = 0$ we have nothing to show since a constant net converges to the lone value of its terms. So, suppose $\alpha \neq 0$ and $r > 0$. By hypothesis, there exists $i_0 \in I$ such that

$$i \geq i_0 \Rightarrow |x_i - x| < \frac{r}{|\alpha|}$$

Hence,

$$i \geq i_0 \Rightarrow |\alpha x_i - \alpha x| = |\alpha| |x_i - x| < |\alpha| \cdot \frac{r}{|\alpha|} = r ///$$

If $z \in \mathbb{C}$, then $z = a + ib$, where $a, b \in \mathbb{R}$ and i is the *imaginary unit* ($i^2 = -1$). The *modulus*, $|z|$, of z is defined as $\sqrt{a^2 + b^2}$. That is,

$$|z| = \sqrt{a^2 + b^2}.$$

The modulus shares many of the properties of the absolute value on \mathbb{R} . Incidentally, they have same notation, $|\cdot|$. From textbooks of beginning *Complex Function Theory*, confirm that

FACT 8 The function

$$d_{|\cdot|} : \mathbb{C} \times \mathbb{C} \rightarrow \mathbb{R},$$

$$(z_1, z_2) \mapsto |z_1 - z_2|$$

is a metric on \mathbb{C} . ///

We denote $\tau_{d_{|\cdot|}}$ by $\tau_{\mathbb{C}}$ and call it the *topology of \mathbb{C}* , in this paper.

FACT 9 Let $z_0 \in \mathfrak{C}$. Then, $(z_i)_{i \in (I, \leq)}$ $\tau_{\mathfrak{C}}$ -converges to z_0

\Leftrightarrow

Whenever given $r > 0$, there exists $i_0 \in I$ such that

$$|z_i - z_0| < r \text{ for all } i \in I, i \geq i_0$$

\Leftrightarrow

$$z_i - z_0 \xrightarrow{\tau_{\mathfrak{C}}} 0.$$

(i.e., the net $(z_i - z_0)_{i \in (I, \leq)}$ $\tau_{\mathfrak{C}}$ -converges to 0). ///

FACT 10 Let $(x_i)_{i \in (I, \leq)}$ and $(y_i)_{i \in (I, \leq)}$ be nets in \mathfrak{C} based on the same directed set (I, \leq) . Suppose $x, y, \alpha \in \mathfrak{C}$ and that

$$x_i \xrightarrow{\tau_{\mathfrak{C}}} x$$

and

$$y_i \xrightarrow{\tau_{\mathfrak{C}}} y.$$

Then,

$$(i) \quad x_i + y_i \xrightarrow{\tau_{\mathfrak{C}}} x + y$$

and

$$\alpha x_i \xrightarrow{\tau_{\mathfrak{C}}} \alpha x. ///$$

K = \mathbb{R} or \mathfrak{C}

Denote by K either of \mathbb{R} and \mathfrak{C} . And we can restate COROLLARY 6 and FACT 9 as

THEOREM 11 Let $x_0 \in K$. The net $(x_i)_{i \in (I, \leq)}$ in K τ_K -converges to $x_0 \Leftrightarrow^1$

Whenever given $r > 0$, there exists $i_0 \in I$ such that

$$|x_i - x_0| < r \text{ for all } i \in I, i \geq i_0$$

\Leftrightarrow^2

$$x_i - x_0 \xrightarrow{\tau_K} 0.$$

(i.e., the net $(x_i - x_0)_{i \in (I, \leq)}$ τ_K -converges to 0.)

Similarly, we can restate THEOREM 7 and FACT 10 as

THEOREM 12 Let $(x_i)_{i \in (I, \leq)}$ and $(y_i)_{i \in (I, \leq)}$ be nets in K based on the same directed set (I, \leq) . Suppose $x, y, \alpha \in K$ and that

$$x_i \xrightarrow{\tau_K} x$$

and

$$y_i \xrightarrow{\tau_K} y.$$

Then,

$$(i) \quad x_i + y_i \xrightarrow{\tau_K} x + y$$

and

$$(ii) \quad \alpha x_i \xrightarrow{\tau_K} \alpha x ///$$

One deduces that

THEOREM 13 If $(t_i)_{i \in (I, \leq)}$ and $(s_i)_{i \in (I, \leq)}$ are nets in K , based on the same directed set (I, \leq) and

$$t_i \xrightarrow{\tau_K} 0 \text{ and } s_i \xrightarrow{\tau_K} 0.$$

Then,

$$t_i + s_i \xrightarrow{\tau_K} 0. ///$$

Call a net $(t_i)_{i \in (I, \leq)}$ in K an *eventually bounded net* if there exists $M > 0$ such that $|t_i| \leq M$ eventually. Immediate is that if a net $(t_i)_{i \in (I, \leq)}$ in K is eventually bounded, so is the net $(|t_i|)_{i \in (I, \leq)}$ in \mathbb{R} .

THEOREM 14(i) If the net $(t_i)_{i \in (I, \leq)}$ in K τ_K -converges, then, it is eventually bounded.

(ii) Suppose $(t_i)_{i \in (I, \leq)}$ and $(s_i)_{i \in (I, \leq)}$ are nets in K based on the same directed set (I, \leq) . Suppose

(α) $(t_i)_{i \in (I, \leq)}$ is eventually bounded

and

(β) $(s_i)_{i \in (I, \leq)}$ is *null* (i.e., $s_i \xrightarrow{\tau_K} 0$).

Then, $(t_i s_i)_{i \in (I, \leq)}$ is null. ///

3 THE PRODUCT TOPOLOGY Let $\Delta \neq \emptyset$ and $(X_\alpha, \tau_\alpha)_{\alpha \in \Delta}$ an indexed family of topological spaces indexed by Δ . With

$\prod_{\alpha \in \Delta} X_\alpha$ we denote the *Cartesian Product* of the indexed family $(X_\alpha)_{\alpha \in \Delta}$ of non-empty sets $X_\alpha, \alpha \in \Delta$. For $\beta \in \Delta, X_\beta$ is called the β th factor set of $\prod_{\alpha \in \Delta} X_\alpha$ and the map

$$p_\beta : \prod_{\alpha \in \Delta} X_\alpha \rightarrow X_\beta$$

$$x = (x(\alpha))_{\alpha \in \Delta} \mapsto x(\beta)$$

is called the *projection of* $\prod_{\alpha \in \Delta} X_\alpha$ onto the β th factor set X_β . Define

$$\mathcal{L} = \{ p_\alpha^{-1}(G_\alpha) : \emptyset \neq G_\alpha \in \tau_\alpha, \alpha \in \Delta \}.$$

The topology on $\prod_{\alpha \in \Delta} X_\alpha$ generated by \mathcal{L} is called the *product topology* of the family $(X_\alpha, \tau_\alpha)_{\alpha \in \Delta}$, denoted $\prod_{\alpha \in \Delta} \tau_\alpha$. And the

pair $(\prod_{\alpha \in \Delta} X_\alpha, \prod_{\alpha \in \Delta} \tau_\alpha)$ is called a *product topological space* or simply called a *product space*.

If $\Delta = \{1, 2\}$, so that we have $(X_\alpha, \tau_\alpha)_{\alpha \in \Delta}$ as the two-terms family $((X_1, \tau_1), (X_2, \tau_2))$, the product set $\prod_{\alpha \in \Delta} X_\alpha$ may be written

$X_1 \times X_2$ and the product topology $\prod_{\alpha \in \Delta} \tau_\alpha$ written $\tau_1 \times \tau_2$, and the product space $(\prod_{\alpha \in \Delta} X_\alpha, \prod_{\alpha \in \Delta} \tau_\alpha)$ written $(X_1 \times X_2, \tau_1 \times \tau_2)$.

A main theorem on net convergence in the product space is

THEOREM 1 (GT) Net Convergence in the Product Topological Space Let $(\prod_{\alpha \in \Delta} X_\alpha, \prod_{\alpha \in \Delta} \tau_\alpha)$ be a product topological

space, $(x_i)_{i \in (I, \leq)}$ a net in $\prod_{\alpha \in \Delta} X_\alpha$ and $x = (x(\alpha))_{\alpha \in \Delta} \in \prod_{\alpha \in \Delta} X_\alpha$. Then, the net $(x_i)_{i \in (I, \leq)}$ $\prod_{\alpha \in \Delta} \tau_\alpha$ -converges to x if and only if its

α th coordinate net, $(x_i(\alpha))_{i \in (I, \leq)}$, τ_α -converges to $x(\alpha)$ for each $\alpha \in \Delta$. That is,

$$x_i \rightarrow x \text{ in } (\prod_{\alpha \in \Delta} X_\alpha, \prod_{\alpha \in \Delta} \tau_\alpha)$$

\Leftrightarrow

$$x_i(\alpha) \rightarrow x(\alpha) \text{ in } (X_\alpha, \tau_\alpha) \text{ for each } \alpha \in \Delta. ///$$

Partial Maps

Let $\emptyset \neq X, X', X^*$, and suppose $x_0 \in X, x_0' \in X'$ and $f : X \times X' \rightarrow X^*$ a map. Associated with this map are the maps

$$f_{x_0} : X' \rightarrow X^*$$

$$x' \mapsto f(x_0, x')$$

and

$$f_{x_0'} : X \rightarrow X^*$$

$$x \mapsto f(x, x_0')$$

called its *partial maps*.

4 CONTINUITY Let (X, τ) and (X', τ') be topological spaces. Suppose $x_0 \in X$ and $f : X \rightarrow X'$ a map.

Cont.a.Defn 1 [1, p. 52] The function f is said to be *continuous at* x_0 if whenever given a neighbourhood V of $f(x_0)$ in (X', τ') , $f^{-1}(V)$ is a neighbourhood of x_0 in (X, τ) .

THEOREM 2 Let (X, τ) and (X', τ') be topological spaces. Suppose $x_0 \in X$ and $f : X \rightarrow X'$ a map. The following are equivalent.

- (1) f is continuous at x_0 .
- (2) Whenever given a neighbourhood V of $f(x_0)$ in (X', τ') , there exists a neighbourhood U of x_0 in (X, τ) such that $f(U) \subseteq V$.

(3) For every $G \in \tau'$ such that $f(x_0) \in G$, there exists $H \in \tau$ such that $x_0 \in H$ and $H \subseteq f^{-1}(G)$. ///

Notation 3 With language and notation still as in the preceding,

(1) By

" $f : (X, \tau) \rightarrow (X', \tau')$ is continuous at x_0 "

shall be meant that $f : X \rightarrow X'$ is continuous at x_0 .

(2) To emphasize that the continuity of $f : X \rightarrow X'$ at x_0 is with respect to the topologies τ and τ' , we may write $f : X \rightarrow X'$ is (τ, τ') -continuous at x_0 .

=Again, with language and notation as in all the preceding, if f is continuous at EVERY point of X , then f is called a *continuous function* and simply said to be *continuous*. And we may write

(i) $f : (X, \tau) \rightarrow (X', \tau')$ is continuous,

or

(ii) $f : X \rightarrow X'$ is (τ, τ') -continuous.

THEOREM 4 *Continuity and Net convergence* Let (X, τ) and (X', τ') be topological spaces, $x_0 \in X$ and $f : X \rightarrow X'$ a map. The following are equivalent.

(1) f is (τ, τ') -continuous at x_0 .

(2) Whenever given a net $(x_i)_{i \in (I, \leq)}$ in X τ -converging to x_0 , the net $(f(x_i))_{i \in (I, \leq)}$ τ' -converges to $f(x_0)$. ///

THEOREM 5 Let (X, τ_d) and $(X', \tau_{d'})$ be pseudometric topological spaces, and $x_0 \in X$. The map $f : (X, \tau_d) \rightarrow (X', \tau_{d'})$ is continuous at x_0 if and only if whenever given $\varepsilon > 0$ there exists a $\delta = \delta(\varepsilon, x_0) > 0$ such that $x \in X$, and $d(x, x_0) < \delta \Rightarrow d'(f(x), f(x_0)) < \varepsilon$.

Proof Deducible from THEOREM 2. ///

COROLLARY 6 Let (X, τ_d) be a pseudometric topological space

and $f : (X, \tau_d) \rightarrow (\mathbb{R}, \tau_{\mathbb{R}})$ a map. Let $x_0 \in X$. Then, f is continuous at x_0 if and only if whenever given $\varepsilon > 0$, there exists $\delta = \delta(\varepsilon, x_0) > 0$ such that

$x \in X$ and $d(x, x_0) < \delta \Rightarrow |f(x) - f(x_0)| < \varepsilon$. ///

COROLLARY 7 Let (X, τ_d) be a pseudometric topological space, and suppose $x_0 \in X$. Then, the map

$f : (X, \tau_d) \rightarrow (\mathbb{R}, \tau_{\mathbb{R}})$

$x \mapsto d(x, x_0)$

is continuous. ///

Recall from the preceding Section 3 that if $\emptyset \neq X, X', X^*, x_0 \in X, x_0' \in X'$ and $f : X \times X' \rightarrow X^*$ is a map, then the maps

$f_{x_0} : X' \rightarrow X^*$

$x' \mapsto f(x_0, x')$

and

$f_{x_0} : X \rightarrow X^*$

$x \mapsto f(x, x_0')$

are called the partial maps of f .

THEOREM 8 Let $(X, \tau), (X', \tau')$ and (X^*, τ^*) be topological spaces. Let $x_0 \in X, x_0' \in X'$, and the map $f : (X \times X', \tau \times \tau') \rightarrow (X^*, \tau^*)$ continuous. Then, the partial maps

$f_{x_0} : (X', \tau') \rightarrow (X^*, \tau^*)$

$x' \mapsto f(x_0, x')$

and

$f_{x_0} : (X, \tau) \rightarrow (X^*, \tau^*)$

$x \mapsto f(x, x_0')$

are continuous maps.

Proof Let $z' \in X'$ and $(z'_i)_{i \in (I, \leq)}$ a net in X' τ' -converging to z' . By 3.1, the net $((x_0, z'_i))_{i \in (I, \leq)}$ $\tau \times \tau'$ -converges to (x_0, z') . By the continuity of f , therefore, $(f(x_0, z'_i))_{i \in (I, \leq)} = (f_{x_0}(z'_i))_{i \in (I, \leq)}$ τ^* -converges to $f(x_0, z') = f_{x_0}(z')$. Similarly, for f_{x_0} . ///

5 VECTOR SPACE Let $(V, +, \theta)$ be an additive Abelian group and $(F, +, \cdot, 0, 1)$ a field. $(V, +, \theta)$ is called a *vector space over the field* $(F, +, \cdot, 0, 1)$ if there exists an *external multiplication*

$$Ext : F \times V \rightarrow V$$

$$(\alpha, v) \mapsto \alpha v$$

of the elements of V by the elements of F satisfying : For $v, \omega \in V$ and $\alpha, \beta \in F$, we have

$$\mathbf{VSP1} \quad 1v = v$$

$$\mathbf{VSP2} \quad (\alpha + \beta)v = \alpha v + \beta v$$

$$\mathbf{VSP3} \quad \alpha(v + \omega) = \alpha v + \alpha \omega$$

$$\mathbf{VSP4} \quad (\alpha\beta)v = \alpha(\beta v)$$

By the notation $(V, +, \theta)_{(F, +, \cdot, 0, 1)}$, at times shortened to V_F , we shall mean in this paper that the additive Abelian group $(V, +, \theta)$ is a vector space over the field $(F, +, \cdot, 0, 1)$.

According to Sterling K. Berberian in [5, p.47], the *real field* $(\mathbb{R}, +, \cdot, 0, 1)$ and the *complex field* $(\mathbb{C}, +, \cdot, 0, 1)$ are the *fields of primary importance in Analysis*. And so, therefore, a fortiori, in the theory of Topological Vector Spaces (TVS), only vector spaces $(V, +, \theta)_{(\mathbb{R}, +, \cdot, 0, 1)}$, and $(V, +, \theta)_{(\mathbb{C}, +, \cdot, 0, 1)}$ are entertained.

By K we have since been denoting either of \mathbb{R} and \mathbb{C} , and so we consider **only** vector spaces V_K . Of course, any field $(F, +, \cdot, 0, 1)$ is a vector space over itself and so F_F is a vector space by our notation. In particular, $\mathbb{R}_{\mathbb{R}}$, $\mathbb{C}_{\mathbb{C}}$, and K_K are vector spaces.

Let V_K be a vector space. By *points of* V_K are meant the elements of the ground set V . That is, by $x \in V_K$ is simply meant $x \in V$. Similarly, by a *net* $(x_i)_{i \in (I, \leq)}$ in V_K is simply meant that $(x_i)_{i \in (I, \leq)}$ is a net in V . Of course, by a *set* of V_K is simply meant a subset of V . Let V_K and W_K be vector spaces. A map $\ell : V_K \rightarrow W_K$ is called a *linear map*, and said to be *linear*, if for $v_1, v_2 \in V_K$ and $\alpha \in K$,

$$(i) \quad \ell(v_1 + v_2) = \ell(v_1) + \ell(v_2)$$

and

$$(ii) \quad \ell(\alpha v) = \alpha \ell(v).$$

Immediate from (i) and (ii) is that, for $v_1, v_2 \in V_K$, $\alpha, \beta \in K$,

$$(iii) \quad \ell(\alpha v_1 + \beta v_2) = \alpha \ell(v_1) + \beta \ell(v_2).$$

FACT 1 Let $(V, +, \theta)_K$ and $(V', +, \theta')_K$ be vector spaces, and $\ell : V_K \rightarrow V'_K$ a linear map. Then, $\ell(\theta) = \theta'$. ///

Let V_K be a vector space. A linear map $\ell : V_K \rightarrow K_K$ is called a *linear functional*. From the preceding FACT 1 follows that

FACT 2 If $(V, +, \theta)_K$ is a vector space and $\ell : (V, +, \theta)_K \rightarrow (K, +, \cdot, 0, 1)_K$ is a linear functional, then, $\ell(\theta) = 0$. ///

6 SEMINORM Let $(V, +, \theta)_{(K, +, \cdot, 0, 1)} = V_K$ be a vector space. A map

$$p : V_K \rightarrow \mathbb{R}$$

such that, for $x, y \in V_K$ and $t \in K$,

$$(i) \quad p(x) \geq 0,$$

$$(ii) \quad p(tx) = |t| p(x),$$

and

$$(iii) \quad p(x + y) \leq p(x) + p(y)$$

is called a *seminorm* on V_K . Clearly, by (ii) and the fact that $0\theta = \theta$,

$$(iv) \quad p(\theta) = 0$$

If

$$(v) \quad p(x) = 0 \Rightarrow x = \theta,$$

then, p is called a *norm* on V_K .

Let p be a seminorm on the vector space V_K . Define

$$d_p : V_K \times V_K \rightarrow \mathbb{R}$$

$$(x, y) \mapsto p(x - y)$$

FACT 1 (i) d_p is a pseudometric on V_K , and
 (ii) if p is a norm, then d_p is a metric. ///

The pseudometric/metric topology, τ_{d_p} , of the pseudometric/metric d_p , is called the *seminorm/norm topology of the seminorm/norm p* .

We here in this paper, briefly write τ_p for τ_{d_p} .

Example 2(i) The absolute value function

$$p : \mathbb{R}_{\mathbb{R}} \rightarrow \mathbb{R}$$

$$x \mapsto |x|$$

is a norm on $\mathbb{R}_{\mathbb{R}}$. Clearly, here $\tau_p = \tau_{d_{||}} = \tau_{\mathbb{R}}$.

(ii) The modulus function

$$p : \mathbb{C}_{\mathbb{C}} \rightarrow \mathbb{R}$$

$$z \mapsto |z|$$

is a norm on $\mathbb{C}_{\mathbb{C}}$. Also, here

$$\tau_p = \tau_{d_{||}} = \tau_{\mathbb{C}}$$

Example 3 Let $\ell : V_K \rightarrow K_K$ be a linear functional on the vector space V_K . Then,

$$p : V_K \rightarrow \mathbb{R}$$

$$v \mapsto |\ell(v)|$$

is a seminorm on V_K .

From 2.5 \Leftrightarrow^3 now follows that

THEOREM 4 If p is a seminorm on the vector space V_K , $x \in V_K$, and $(x_i)_{i \in (I, \leq)}$ a net in V_K , then,

$$x_i \xrightarrow{\tau_p} x \Leftrightarrow p(x_i - x) \xrightarrow{\tau_R} 0. ///$$

We now prove

THEOREM 5 Let

(i) V_K be a vector space,

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(ii) p a seminorm on V_K ,

(iii) $(t_i)_{i \in (I, \leq)}$ a net in K τ_K -converging to t ,

(iv) $(x_i)_{i \in (I, \leq)}$ a net in V_K τ_p -converging to x .

Then, the net $(tx_i)_{i \in (I, \leq)}$ τ_p -converges to tx .

Proof By THEOREM 4, it suffices to show that

$$p(tx_i - tx) \xrightarrow{\tau_R} 0.$$

And this we proceed to do. Clearly,

$$p(tx_i - tx) = p(tx_i - t_i x + t_i x - tx)$$

$$= p(t_i(x_i - x) + (t_i - t)x)$$

$$\leq p(t_i(x_i - x)) + p((t_i - t)x)$$

$$= |t_i| p(x_i - x) + |t_i - t| p(x).$$

That is,

$$p(tx_i - tx) \leq |t_i| p(x_i - x) + |t_i - t| p(x) \quad \dots(\Delta)$$

By THEOREM 4,

$$p(x_i - x) \xrightarrow{\tau_R} 0 \quad \dots(\nabla)$$

By 2.14(i), since $t_i \xrightarrow{\tau_R} t$, the net $(t_i)_{i \in (I, \leq)}$ in K is eventually bounded, and so, the net $(|t_i|)_{i \in (I, \leq)}$ in \mathbb{R} is also eventually bounded. Hence, it follows from 2.14(ii) and (∇) that

$$|t_i| p(x_i - x) \xrightarrow{\tau_R} 0 \quad \dots(\rho^1)$$

Clearly,

$$|t_i - t| p(x) \xrightarrow{\tau_R} 0 \quad \dots(\rho^2)$$

By 2.13, therefore, (ρ^1) and (ρ^2) give

$$|t_i|p(x_i - x) + |t_i - t|p(x) \xrightarrow{\tau_R} 0 \quad \dots(\Delta\Delta)$$

Clearly (Δ) and $(\Delta\Delta)$ give

$$p(t_i x_i - t x) \xrightarrow{\tau_R} 0. \quad ///$$

THEOREM 6 Let V_K be a vector space, $x, y \in V_K$ and p a semi-norm on V_K . Suppose $(x_i)_{i \in (I, \leq)}$ and $(y_i)_{i \in (I, \leq)}$ are nets in V_K , based on same directed set (I, \leq) , such that

$$x_i \xrightarrow{\tau_p} x \text{ and } y_i \xrightarrow{\tau_p} y \quad \dots(\Sigma^1)$$

Then,

$$x_i + y_i \xrightarrow{\tau_p} x + y \quad \dots(\Sigma^2)$$

Proof To prove (Σ^2) , it suffices by THEOREM 4 to show that

$$p((x_i + y_i) - (x + y)) \xrightarrow{\tau_R} 0 \quad \dots(\Sigma^3)$$

And this, we do. Again by THEOREM 4 and hypotheses (Σ^1)

$$p(x_i - x) \xrightarrow{\tau_R} 0 \quad \dots(\Sigma^4)$$

and

$$p(y_i - y) \xrightarrow{\tau_R} 0 \quad \dots(\Sigma^5)$$

By 2.13, therefore, (Σ^4) and (Σ^5) give

$$p(x_i - x) + p(y_i - y) \xrightarrow{\tau_R} 0 \quad \dots(\Sigma^6)$$

Clearly,

$$p((x_i + y_i) - (x + y)) = p((x_i - x) + (y_i - y)) \leq p(x_i - x) + p(y_i - y).$$

That is,

$$p((x_i + y_i) - (x + y)) \leq p(x_i - x) + p(y_i - y) \quad \dots(\Sigma^7)$$

Clearly from (Σ^6) and (Σ^7) is that

$$p((x_i + y_i) - (x + y)) \xrightarrow{\tau_R} 0 \text{ which is } (\Sigma^3). \quad ///$$

7 TOPOLOGICAL VECTOR SPACE Let V_K be a vector space and τ a topology on V_K . The topology τ is said to be compatible with the vector space structure of V_K provided addition

$$Ad : (V_K \times V_K, \tau \times \tau) \rightarrow (V_K, \tau)$$

$$(v, \omega) \mapsto v + \omega$$

and scalar multiplication

$$Sc : (K \times V_K, \tau_K \times \tau) \rightarrow (V_K, \tau)$$

$$(\alpha, v) \mapsto \alpha v$$

are continuous mappings. If this is so, we call τ a vector topology, and the topological space (V_K, τ) called a topological vector space.

THEOREM 1 If p is a seminorm on the vector space V_K , then the seminorm topology, τ_p , of p on V_K , is a vector topology, and (V_K, τ_p) is a topological vector space.

Proof We have to show that addition

$$Ad : (V_K \times V_K, \tau_p \times \tau_p) \rightarrow (V_K, \tau_p)$$

$$(v, \omega) \mapsto v + \omega$$

and scalar multiplication

$$Sc : (K \times V_K, \tau_K \times \tau_p) \rightarrow (V_K, \tau_p)$$

$$(\alpha, v) \mapsto \alpha v$$

are continuous mappings. For Ad , let $(v, \omega) \in V_K \times V_K$ and $((v_i, \omega_i)_{i \in (I, \leq)})$ a net in $V_K \times V_K$. Suppose

$$(v_i, \omega_i) \xrightarrow{\tau_p \times \tau_p} (v, \omega) \quad \dots(\delta^1)$$

Then, by 3.1, therefore,

$$v_i \xrightarrow{\tau_p} v$$

and $\omega_i \xrightarrow{\tau_p} \omega.$

By 6.6, therefore,

$$Ad((v_i, \omega_i)) = v_i + \omega_i \xrightarrow{\tau_p} v + \omega \quad \dots(\delta^2)$$

Clearly, by 4.4, (δ^1) and (δ^2), Ad is a continuous mapping. Similarly, Sc is a continuous mapping. ///

One also deduces from 2.12 that

THEOREM 2 τ_K is a vector topology on K_K , and so (K_K, τ_K) is a topological vector space. ///

We conclude this paper with two applications of the *Continuity of the partial maps*.

THEOREM 3 *Continuity of Translation* Let (V_K, τ) be a topological vector space, and suppose $a \in V_K$. Then, translation $T_a : (V_K, \tau) \rightarrow (V_K, \tau)$

$$\omega \mapsto a + \omega$$

is continuous (Indeed, a *homeomorphism*).

Proof By hypothesis, addition

$$Ad : (V_K \times V_K, \tau \times \tau) \rightarrow (V_K, \tau)$$

$$(v, \omega) \mapsto v + \omega$$

is continuous. By 4.8, therefore,

$$Ad_a : (V_K, \tau) \rightarrow (V_K, \tau)$$

$$\omega \mapsto a + \omega$$

is continuous. Clearly, $T_a = Ad_a$. ///

Let (V_K, τ) be a topological vector space and $\alpha \in K$. From the continuity of the scalar multiplication

$$Sc : (K_K \times V_K, \tau_K \times \tau) \rightarrow (V_K, \tau)$$

$$(t, v) \mapsto tv$$

and 4.8, therefore, follows that

$$Sc_\alpha : (V_K, \tau) \rightarrow (V_K, \tau)$$

$$v \mapsto \alpha v$$

is continuous. If we take $\alpha = -1$, then we have

THEOREM 4 *Continuity of the Additive Inversion* Let (V_K, τ) be a topological vector space. The additive inversion

$$h : (V_K, \tau) \rightarrow (V_K, \tau)$$

$$v \mapsto -v$$

is continuous. ///

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